

# A Novel Approach to Perform Rank-one Updates for Machine Learning

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## Introduction

- Computational errors encountered in Machine Learning (ML) can lead these algorithms astray.
- Roundoff errors due to fixed-precision computations have been given little attention.
- For the most part, these errors are associated with solving System of Linear Equations (SLE).
- Transforming ML algorithms into unlimited precision is computationally expensive.
- Rank-one updates provide computational savings by taking advantage that the SLEs solved are close to each other.
- There is a need to perform these updates without any errors.

## Objective

The goal is to develop an algorithm which performs Rank-one updates which is not only computationally fast but is also free from rounding errors.

## Idea

- The Round-off Error Free (REF) framework is founded on the Integer Preserving Gaussian Elimination algorithm.
- This framework is used to solve rational SLEs using integer arithmetic without any rounding errors.
- In this framework, there is a REF LU factorization that can be efficiently computed to solve SLEs.
- Our main idea is to update the factorization coefficients for the types of changes that are encountered in ML algorithms.

## Methodology and Results

- Building the REF-LU factorization from scratch takes  $O(n^3)$  operations; hence, we focus on developing an update algorithm that takes only  $O(n^2)$  operations without any rounding errors.
- Let  $A$  be a  $(n \times n)$  nonsingular matrix whose factorization is known, the Rank-one update of  $A$  is defined as,

**Rank-one Update**

REF-LU(A)  $\xrightarrow{\hspace{2cm}}$  REF-LU(B)

$$B = A + \sigma \gamma \gamma^T$$

$\sigma$  is an integer scalar

$\gamma$  is a column vector with  $n$  entries

### Example

$$\begin{bmatrix} 2 & 7 & 3 \\ 5 & 4 & 9 \\ 1 & 6 & 8 \end{bmatrix} + 1 * \begin{bmatrix} 4 \\ 1 \\ 3 \end{bmatrix} * [4 \ 1 \ 3] = \begin{bmatrix} 18 & 11 & 15 \\ 9 & 5 & 12 \\ 13 & 9 & 17 \end{bmatrix}$$

$A \qquad \qquad \sigma \ \gamma \qquad \qquad \gamma^T \qquad \qquad B$

### Computational Results

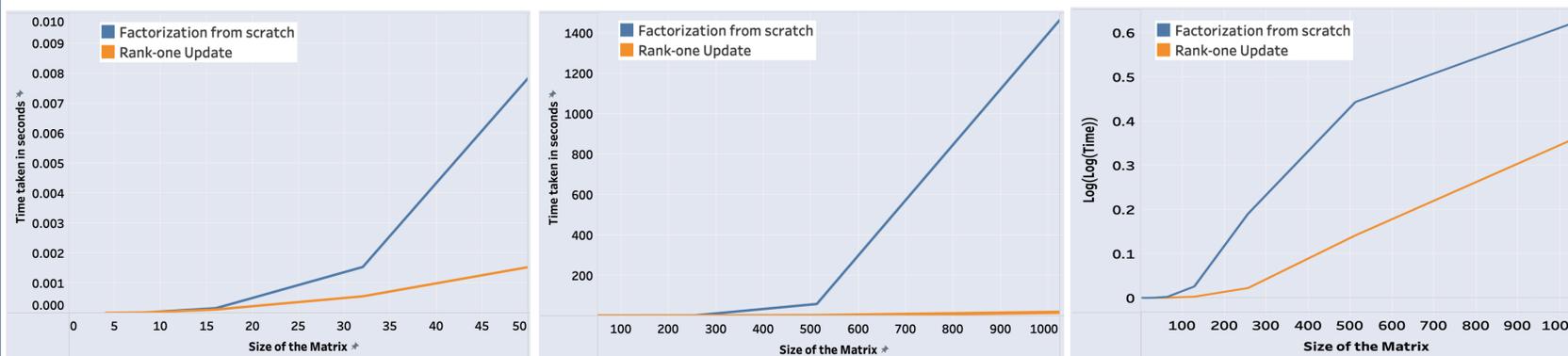
Size of the matrix	Time taken in seconds	
	From scratch	Rank-one update
4	2.06E-6	6.41E-06
8	1.33E-05	1.96E-05
16	1.61E-04	1.17E-04
32	1.54E-03	5.58E-04
64	0.0127	0.002
128	0.15	0.014
256	2.54	0.128
512	58.50	1.43
1024	1463	17.6

We have devised an update algorithm that has been tested numerically.

**Highlight #1** Initially when the size of the matrix (N) is small (less than 15), there is not much computational difference between our method and factorizing B from scratch.

**Highlight #2** When size increases, the time taken to perform the factorization from scratch increases very fast.

**Highlight #3** The third graph represents a log log scale of the time taken and from this it is evident that performing a Rank-one update is faster than performing factorization from scratch.



## Implementation Details

- Nine different matrices of size ranging from  $2^2$  to  $2^{10}$  were used to perform computations.
- The elements of the matrix were selected randomly from the numbers -10 to +10.
- Each size was tested with 32 different seeds.
- The time statistics for each size of the matrix was calculated by averaging the 32 different seeds
- To perform high precision operations, the algorithm was programmed in C++ using the GNU GMP library .
- The computations were performed via the ASU Research Computing Cluster

## Future Work

- Code other algorithms and compare the results.
- Generalize this approach to perform other low rank updates.

## References

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- Escobedo, A. R., & Moreno-Centeno, E. (2017). Roundoff-error-free basis updates of LU factorizations for the efficient validation of optimality certificates. *SIAM Journal on Matrix Analysis and Applications*, 38(3), 829-853.
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